

**HYBRID MPPT ALGORITHMS FOR BIDIRECTIONAL DC CONVERTER**

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Abstract—The battery operated vehicles, popularly known as EV has reduced the carbon emission tremendously in transportation industry. The batteries are charged either through the grid or the best option is hybrid green resources like PV, fuel cell, Super capacitors, etc., For smooth functioning of hybrid resources, Bi-directional DC-DC converters are primarily required so as to maintain the DC-bus voltage both at load terminal as well as at input terminal where PV-battery are connected. In this paper performance analysis of a dual switch DC-converter is presented with bi-directional topology. The converter designed to perform buck-boost operation with wide range of voltage diversity. While combining hybrid resources, environmental constraints of PV is also considered and MPPT is designed with neural network tuning to obtain the maximum operating point under variable irradiance conditions. This will help in extending the efficiency of the DC-converter proposed. The results are obtained in MATLAB simulation tool.

Keywords— *Renewable Generation System, Bi-Directional DC Converters (BDDC), Electric Vehicles, Neural Network (NN), Hybrid Battery Storage System (HBSS), Maximum Power Point Tracking (MPPT).*

I. INTRODUCTION

Transformation of Traditional Power Grid System (TPGS) into the hybrid system due to the involvement of Renewable Generation System (RGS) and their respective conversion system requires frequent high rating converters both DC as well as DC↔AC. At generation side green evolution is at its peak and around 40% of total electricity is now obtained from green resources. But, at demand side DC applications are still in adaptation phase so as to reduce the carbon foot print. DC-applications requires Bi-Directional DC Converters (BDDC) which can flip its voltage as per the requirement. All the renewable generation needs DC-batteries to fulfil the environmental gap so as to increase the reliability in supply. For charging and discharging of these batteries BDDC are required. Other than usage in storage system, BDDC are frequently used in Electric Vehicles (EV). In EV technology, BDDC has dual applications. One in charging and discharging of Hybrid Battery Storage System (HBSS), another is switching voltages during starting, running and braking modes.

With added electrification in automotive designs, the power demands for start↔stop of EV and hybrid electric vehicles have increased significantly [1]. For ignition and braking in EV, BDDC switches frequently between the buck and boost mode. Hence a precise with high switching frequency and efficient BDDC is necessary for world wide adoption of EV with over all ranges of automobile including Low/Medium/High vehicles [2]. For example, in LV-EV for 200 A of current distributed on a 12-V bus requires a larger cross-section copper wire, hence system becomes costly. Besides high-current-distribution conduction loss also increases, hence 12-V system becomes less. A 48-V power system can resolve this issue therefore a BDDC is added to power the high-power components instead. Table 1 presents this case study where a conversion of DC-DC voltage (12V ↔ 48 V) is presented to coordinated the voltage switch during operational constraints in EV [3].

DC↔AC↔DC conversion [13]. A high voltage conversion ratio can be achieved by adjusting the turns ratio of the transformer [14]. The classification detail classification of BDDC is shown in Fig. 1.

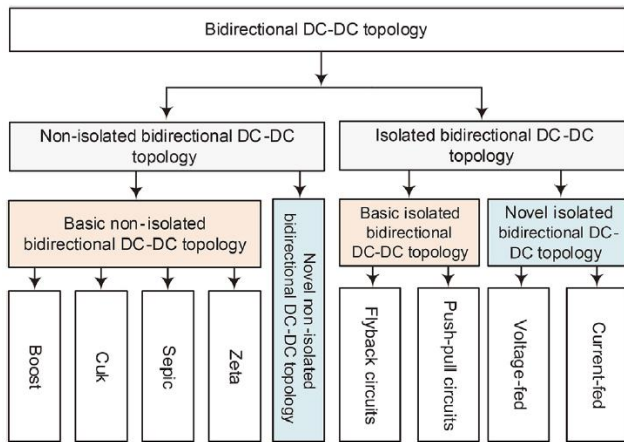


Fig. 1. Classification of BDDC topologies.

This paper presents a novel BDDC topology having dual switch configuration which can be implemented to the wide range of voltage conversion with high gain. The state of the art of the topology proposed is that it is designed with NN interfacing for tuning of PID controller in-order to obtain precise pulse train for the power semiconductor-switches. Also, the boost↔buck conversion is very smooth with high conversion gain and efficiency.

III. PROPOSED WORK

This paper presents a DC-converter with bidirectional feature for charging and discharging of batteries connected at input side as well as output side. Input side battery is powered by PV power where as at the output terminal of BDDC, battery of EV is connected. The schematic diagram of proposed system is shown in figure 2. The BDDC designed, controls the battery status at both the ends and maintains the DC-voltage at EV side at variable voltage conditions. PV side battery, takes into account the variation in irradiance, results are also presented without connecting the PV side battery and the output obtained from PV is directly fed to the BDDC. The PV system includes the PV-array and Maximum Power Point Tracking (MPPT) algorithm. Incremental and conductance MPPT algorithm is employed to track the maximum voltage and current of solar. The PID controller is used to control the gate pulses of the two switches of BDDC. The NN helps in tuning of quickly and accurately gains of PID controller with varying operating conditions. The input layer receives the data to be processed, the hidden layer treats the network, and the output NN layer displays the network replies. This is the structure of a NN which is shown in figure 3. Because NN doesn't require a physical model or complicated mathematical calculations, it is frequently utilised for MPPT control.

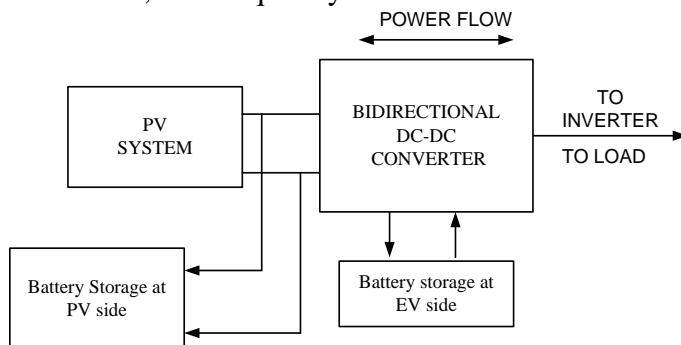


Fig. 2. Schematic of proposed BDDC topologies.

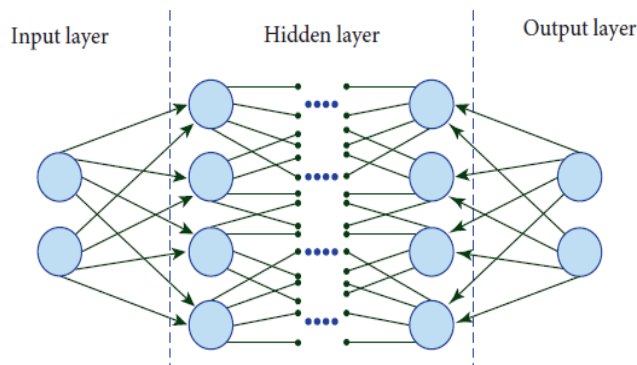


Fig. 3. Neural topology.

IV. SIMULATION RESULTS

The simulation results for the proposed system had been obtained in matlab simulation software. The proposed BDDC work on dual mode of boost↔buck considering variations in solar irradiations and change in EV requirement during ignition and breaking. During ignition high voltage is required and during breaking power is fed back to the system, hence bidirectional converters help in simultaneous charging and discharging of the batteries. The proposed BDDC is powered by PV-power as shown in figure 4. The two switches S1 and S2 controls the boost↔buck operation during.

The proposed BDDC is analysed for constant and variable solar irradiations. A PV module is considered with max. voltage of 30.7 V and max current rated is 8.15 A for voltage range of 70-200 V. The design parameters for the BDDC are given in table 2.

TABLE II. BDDC DESIGN PARAMETERS

| Parameters | Values |
|-------------------|--------------|
| F | 50Hz |
| Fs | 10 KHz |
| D1 | 0.4 |
| D2 | 0.6 |
| C1 | 1000 μ F |
| C2 | 100 μ F |
| R1 | 0.01 |
| R2 | 0.1 |
| L1 | 20mH |
| Proportional gain | 1.5 |
| Integral gain | 25 |

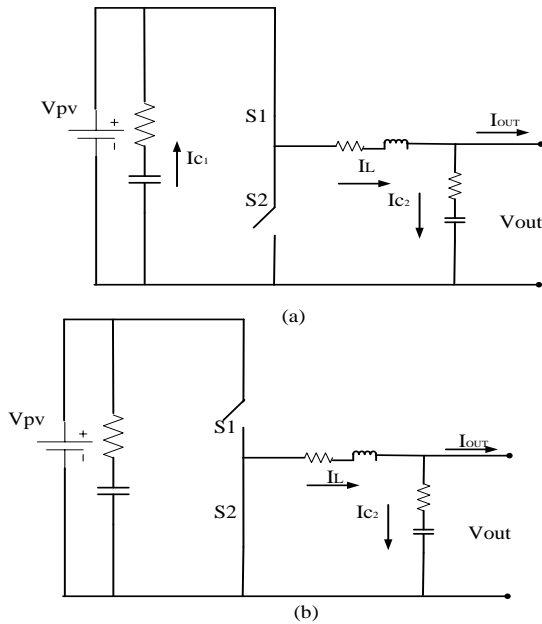


Fig. 4. Single line diagram of proposed BDDC topologies.

A. Boost operation with constant Irradiations

The solar irradiance is kept constant at 1000 w/m^2 to test the performance of the BDDC in boost mode. The PV-array generates 9000 w at 70 V . This voltage is fed to the BDDC which boost it upto 200 V as shown in figure 5. The switching status under this condition is shown in figure 6.

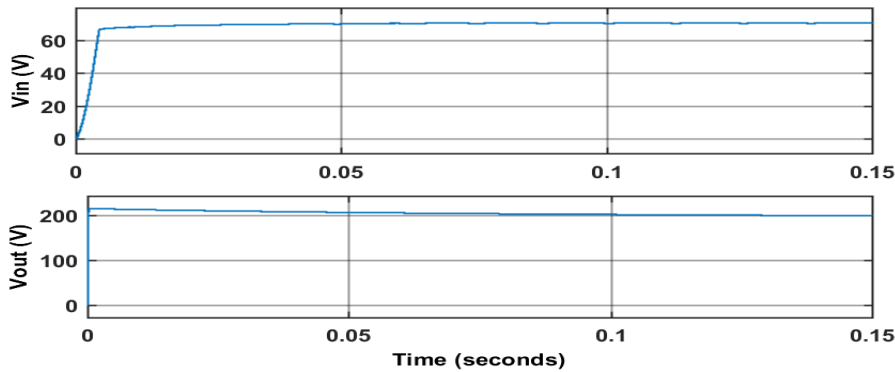


Fig. 5. Input/Output voltage under boost mode with constant irradiations.

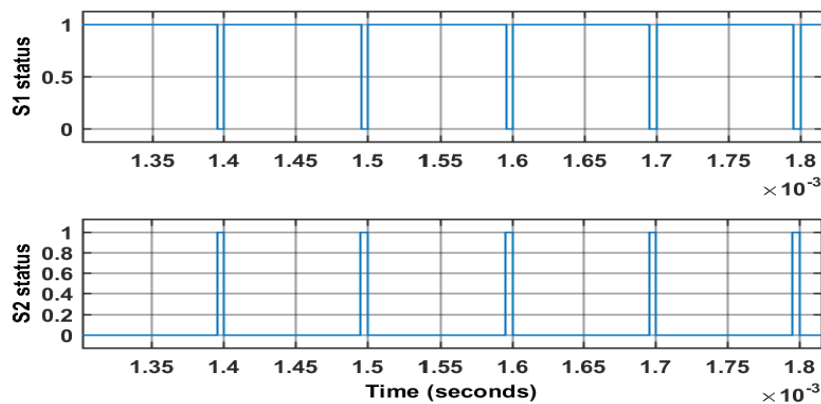


Fig. 6. Switch status under boost mode.

B. Buck operation with constant Irradiations

In buck mode, the flow of current is reverse from EV battery to towards PV system. This is the case when braking is applied, or the battery is overcharged so as to maintain the voltage level as predefined one at both the terminals. In this mode also, the solar irradiance is kept constant. The input/output voltage under such condition is shown in figure 7 with respective currents as per the figure 8. From the

figure 8, it can be seen that the current i_1 at input side is flowing in reverse direction which shows the bidirectional feature of the BDDC where input voltage is 70 V which is reduced to 25 V. The inductor current under this condition is shown in figure 9.

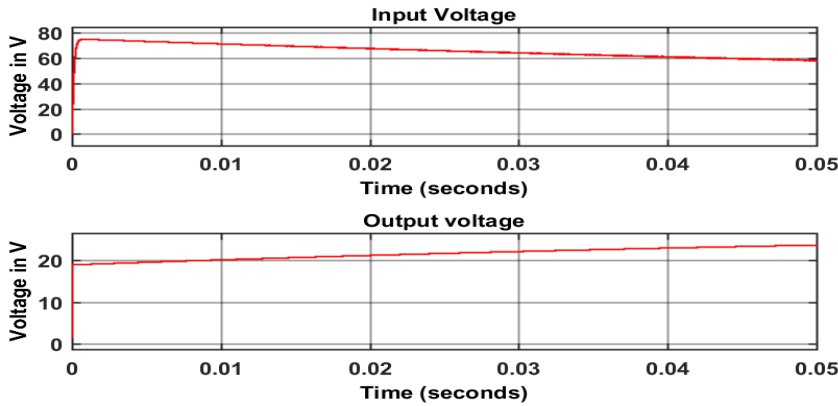


Fig. 7. Input/output voltage under buck mode with constant irradiance.

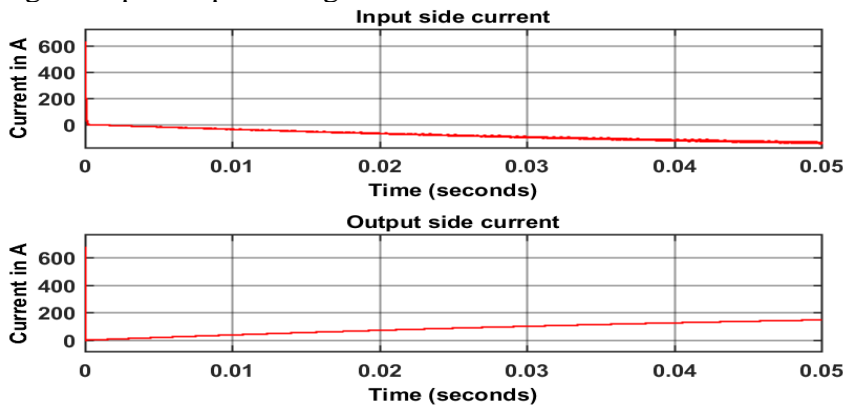


Fig. 8. Input/output current for buck mode with constant irradiance.

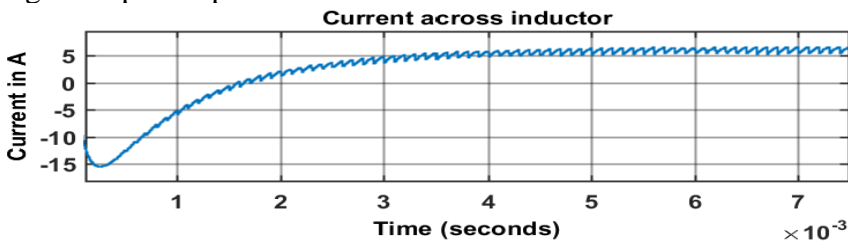


Fig. 9. Inductor current for buck mode.

C. Boost/Buck operation with Variable Irradiations

Now the designed system has been analysed for variable irradiance for boost mode. The irradiance is varied from 1000-600 w/m^2 as shown in graph of figure 10. The switch status for this condition is shown in figure 11.

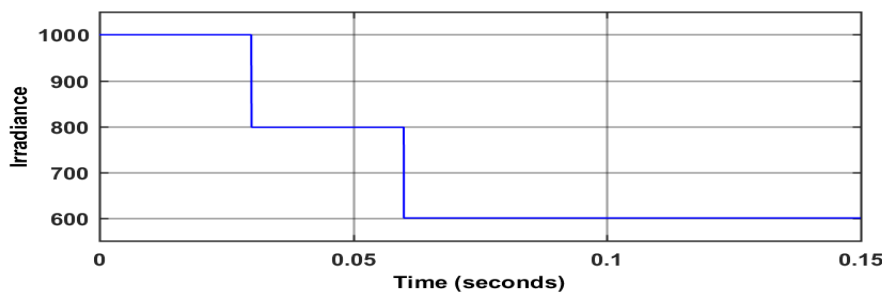


Fig. 10. Variable irradiance graph.

The voltage at input and output side for boost mode under variable irradiance condition is shown in figure 12. And in buck mode the voltage at input side is 150 V, which is reduced to 20 V as shown in figure 13. From both the figures of voltages in boost and buck mode, it can be seen that though irradiance is varying but does not affect the voltages at the terminals of the BDDC. The inductor current under this condition is shown in figure 14.

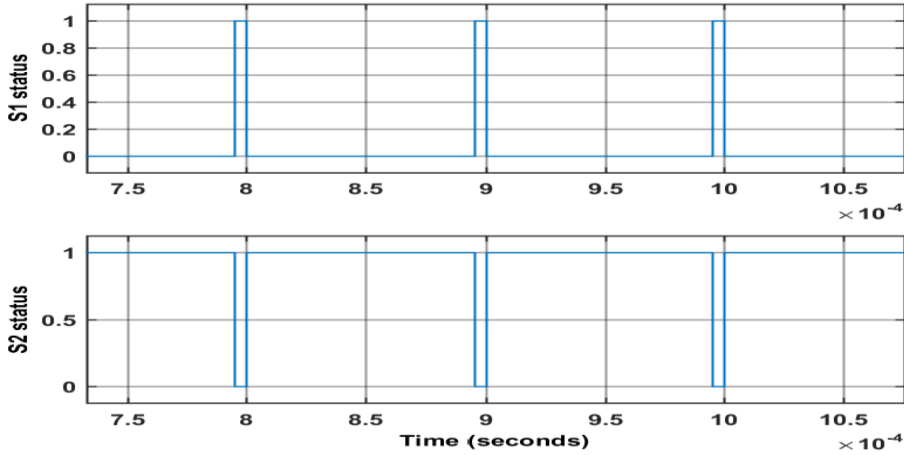


Fig. 11. Switch status under the condition of variable irradiance with buck mode.

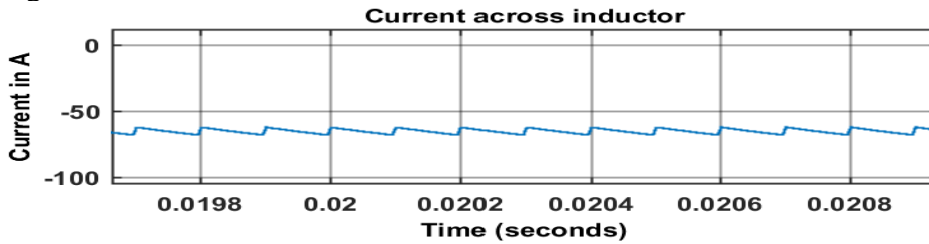


Fig. 12. Inductor current for variable irradiance.

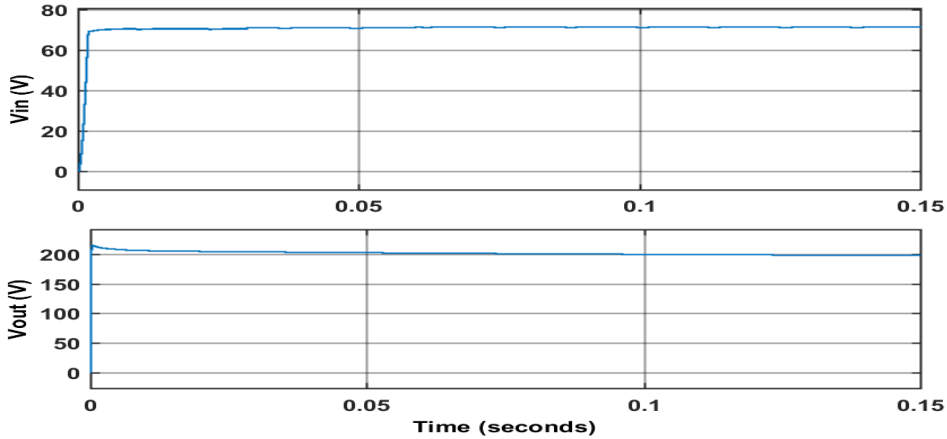


Fig. 13. Input/Output voltage under boost mode with variable irradianations.

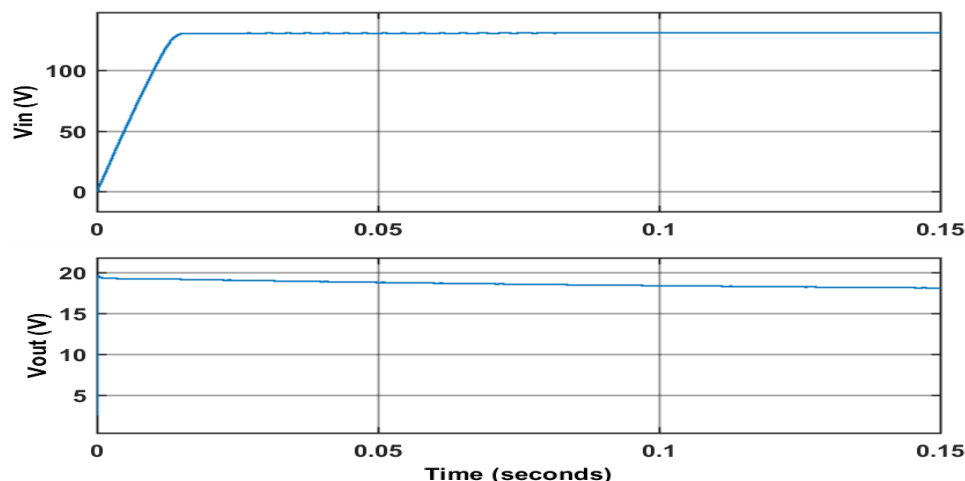


Fig. 14. Input/Output voltage under buck mode with variable irradianations.

V. SIMULATION RESULTS

The DC battery system is increasing in numerous operations as a result of green energy system and so the bidirectional DC converters. This paper presents one such application of BDDC in EV. The battery system used in input side of the BDDC is charged via solar power and at the output side battery powers the EV. Solar energy is continuously varying in nature hence a MPPT incremental and conduct. Algorithm is employed to track the max. point of voltage and current generation from PV. To increase the tracking and for fast response, In this paper neural network is employed in conjunction with the MPPT. The proposed BDDC is tested under varying and constant irradiance for both boost↔buck operation. The output obtained is unaffected by irradiation variation and a smooth boost↔buck operation is verified. Results obtained at various voltage ranges to justifies the diversity of the design which fulfil the requirement of EV.

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